



The Natural Operators Similar to the Twisted Courant Bracket One

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Abstract. Given natural numbers $m \geq 3$ and $p \geq 3$, all $\mathcal{M}f_m$ -natural operators A_H sending p -forms $H \in \Omega^p(M)$ on m -manifolds M into bilinear operators $A_H : (\mathcal{X}(M) \oplus \Omega^1(M)) \times (\mathcal{X}(M) \oplus \Omega^1(M)) \rightarrow \mathcal{X}(M) \oplus \Omega^1(M)$ transforming pairs of couples of vector fields and 1-forms on M into couples of vector fields and 1-forms on M are founded. If $m \geq 3$ and $p \geq 3$, then that any (similar as above) $\mathcal{M}f_m$ -natural operator A which is defined only for closed p -forms H can be extended uniquely to the one A which is defined for all p -forms H is observed. If $p = 3$ and $m \geq 3$, all $\mathcal{M}f_m$ -natural operators A (as above) such that A_H satisfies the Leibniz rule for all closed 3-forms H on m -manifolds M are extracted. The twisted Courant bracket $[-, -]_H$ for all closed 3-forms H on m -manifolds M gives the most important example of such $\mathcal{M}f_m$ -natural operator A .

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1. Introduction

The “doubled” tangent bundle $T \oplus T^*$ over m -dimensional manifolds (m -manifolds) is full of interest because it has the natural inner product, and the Courant bracket, see [1]. Besides, generalized complex structures are defined on $T \oplus T^*$, generalizing both (usual) complex and symplectic structures, see e.g. [3, 4].

In Sect. 2, the description from [2] of all $\mathcal{M}f_m$ -natural bilinear operators

$$A : (\mathcal{X}(M) \oplus \Omega^1(M)) \times (\mathcal{X}(M) \oplus \Omega^1(M)) \rightarrow \mathcal{X}(M) \oplus \Omega^1(M),$$

transforming pairs of couples of vector fields and 1-forms on m -manifolds M into couples of vector fields and 1-forms on M will be shortly cited. The most important example of such $\mathcal{M}f_m$ -natural bilinear operator A is given by the Courant bracket $[-, -]^C$, see Example 2.2. This Courant bracket was used in [1] to define the concept of Dirac structures being hybrid of both symplectic and Poisson structures.

In Sect. 2 we also deduce that the “trivial” Lie algebroid $(TM \oplus T^*M, 0, 0)$ is the only $\mathcal{M}f_m$ -natural Lie algebroid $(EM, [[-, -]], a)$ with $EM := TM \oplus T^*M$.

In Sect. 3, using essentially the results from [2], if $m \geq 3$ and $p \geq 3$, we find all $\mathcal{M}f_m$ -natural operators A sending p -forms $H \in \Omega^p(M)$ on m -manifolds M into bilinear maps

$$A_H : (\mathcal{X}(M) \oplus \Omega^1(M)) \times (\mathcal{X}(M) \oplus \Omega^1(M)) \rightarrow \mathcal{X}(M) \oplus \Omega^1(M).$$

The most important example of such A is given by the H -twisted Courant bracket $[-, -]_H$ for all 3-forms H on m -manifolds M , see Example 3.2. Properties of $[-, -]_H$ (as the Leibniz rule for closed 3-forms H) were used in [7, 8] to define the concept of exact Courant algebroid.

In Sect. 4, we observe that if $m \geq 3$ and $p \geq 3$, then any (similar as above) $\mathcal{M}f_m$ -natural operator A which is defined only for closed p -forms H can be extended uniquely to the one A which is defined for all p -forms H .

In Sect. 5, if $p = 3$ we extract all $\mathcal{M}f_m$ -natural operators A as above satisfying the Leibniz rule

$$A_H(\rho_1, A_H(\rho_2, \rho_3)) = A_H(A_H(\rho_1, \rho_2), \rho_3) + A_H(\rho_2, A_H(\rho_1, \rho_3)),$$

for any closed $H \in \Omega^3(M)$, $\rho_1, \rho_2, \rho_3 \in \mathcal{X}(M) \oplus \Omega^1(M)$ and $M \in \text{obj}(\mathcal{M}f_m)$.

From now on, (x^i) ($i = 1, \dots, m$) denote the usual coordinates on \mathbf{R}^m and $\partial_i = \frac{\partial}{\partial x^i}$ are the canonical vector fields on \mathbf{R}^m .

All manifolds considered in this paper are assumed to be finite dimensional second countable Hausdorff without boundary and smooth (of class \mathcal{C}^∞). Maps between manifolds are assumed to be smooth (of class \mathcal{C}^∞).

2. The Natural Bilinear Operators Similar to the Courant Bracket

The general concept of natural operators can be found in the fundamental monograph [5]. In the paper, we need two particular cases of natural operators presented in Definitions 2.1 (below) and 3.1 (in the next section).

Let $\mathcal{M}f_m$ be the category of m -dimensional \mathcal{C}^∞ manifolds as objects and their immersions of class \mathcal{C}^∞ as morphisms ($\mathcal{M}f_m$ -maps).

Definition 2.1. A natural (called also $\mathcal{M}f_m$ -natural) operator A sending pairs of couples of vector fields and 1-forms on m -manifolds M into couples of vector fields and 1-forms on M is a $\mathcal{M}f_m$ -invariant family of operators (functions)

$$A : (\mathcal{X}(M) \oplus \Omega^1(M)) \times (\mathcal{X}(M) \oplus \Omega^1(M)) \rightarrow \mathcal{X}(M) \oplus \Omega^1(M),$$

for all m -manifolds M , where $\mathcal{X}(M) \oplus \Omega^1(M)$ is the vector space of couples (X, ω) of vector fields X on M and 1-forms ω on M . Such $\mathcal{M}f_m$ -natural operator A is called bilinear if A is bilinear (i.e., $A(\rho^1, -)$ and $A(-, \rho^2)$ are linear (over the field \mathbf{R} of real numbers) functions $\mathcal{X}(M) \oplus \Omega^1(M) \rightarrow \mathcal{X}(M) \oplus \Omega^1(M)$ for any fixed $\rho^1, \rho^2 \in \mathcal{X}(M) \oplus \Omega^1(M)$) for any m -manifold M . Such $\mathcal{M}f_m$ -natural operator A is called skew-symmetric if A is skew-symmetric for any m -manifold M .

The $\mathcal{M}f_m$ -invariance of A means that if $(X^1 \oplus \omega^1, X^2 \oplus \omega^2)$ and $(\bar{X}^1 \oplus \bar{\omega}^1, \bar{X}^2 \oplus \bar{\omega}^2)$ are φ -related by an $\mathcal{M}f_m$ -map $\varphi : M \rightarrow \bar{M}$ (i.e., $\bar{X}^i \circ \varphi = T\varphi \circ X^i$ and $\bar{\omega}^i \circ \varphi = T^*\varphi \circ \omega^i$ for $i = 1, 2$), then so are $A(X^1 \oplus \omega^1, X^2 \oplus \omega^2)$ and $A(\bar{X}^1 \oplus \bar{\omega}^1, \bar{X}^2 \oplus \bar{\omega}^2)$.

The most important example of such $\mathcal{M}f_m$ -natural bilinear operator A is given by the (skew-symmetric) Courant bracket $[-, -]^C$ for any m -manifold M .

Example 2.2. On the vector bundle $TM \oplus T^*M$ there exist canonical symmetric and skew-symmetric pairings

$$\langle X^1 \oplus \omega^1, X^2 \oplus \omega^2 \rangle_{\pm} = \frac{1}{2}(i_{X^2}\omega^1 \pm i_{X^1}\omega^2)$$

for any $X^1 \oplus \omega^1, X^2 \oplus \omega^2 \in \mathcal{X}(M) \oplus \Omega^1(M)$, where i is the interior derivative. Further, the (skew-symmetric) Courant bracket is given by

$$\begin{aligned} [X^1 \oplus \omega^1, X^2 \oplus \omega^2]^C \\ = [X^1, X^2] \oplus \left(\mathcal{L}_{X^1}\omega^2 - \mathcal{L}_{X^2}\omega^1 + d \langle X^1 \oplus \omega^1, X^2 \oplus \omega^2 \rangle_- \right) \end{aligned}$$

for any $X^1 \oplus \omega^1, X^2 \oplus \omega^2 \in \mathcal{X}(M) \oplus \Omega^1(M)$, where $[-, -]$ is the usual bracket on vector fields, \mathcal{L} is the Lie derivative and d is the exterior derivative.

Theorem 2.3 [2]. *If $m \geq 2$, any $\mathcal{M}f_m$ -natural bilinear operator A in the sense of Definition 2.1 is of the form*

$$\begin{aligned} &A(\rho^1, \rho^2) \\ &= a[X^1, X^2] \oplus \left(b_1\mathcal{L}_{X^2}\omega^1 + b_2\mathcal{L}_{X^1}\omega^2 + b_3d \langle \rho^1, \rho^2 \rangle_+ + b_4d \langle \rho^1, \rho^2 \rangle_- \right) \end{aligned}$$

for (uniquely determined by A) real numbers a, b_1, b_2, b_3, b_4 , where $\rho^i = X^i \oplus \omega^i \in \mathcal{X}(M) \oplus \Omega^1(M)$ for $i = 1, 2$ are arbitrary, and where $\langle -, - \rangle_+$ and $\langle -, - \rangle_-$ are as in Example 2.2.

Corollary 2.4 [2]. *If $m \geq 2$, any $\mathcal{M}f_m$ -natural skew-symmetric bilinear operator A in the sense of Definition 2.1 is of the form*

$$\begin{aligned} &A(X^1 \oplus \omega^1, X^2 \oplus \omega^2) \\ &= a[X^1, X^2] \oplus (b(\mathcal{L}_{X^1}\omega^2 - \mathcal{L}_{X^2}\omega^1) + cd \langle X^2 \oplus \omega^1, X^1 \oplus \omega^2 \rangle_-) \end{aligned}$$

for (uniquely determined by A) real numbers a, b, c .

Roughly speaking, Corollary 2.4 says that if $m \geq 2$, then any $\mathcal{M}f_m$ -natural skew-symmetric bilinear operator A in the sense of Definition 2.1 coincides with the one given by Courant bracket $[-, -]^C$ up to three real constants.

Definition 2.5. A $\mathcal{M}f_m$ -natural bilinear operator A in the sense of Definition 2.1 satisfies the Leibniz rule if

$$A(\rho_1, A(\rho_2, \rho_3)) = A(A(\rho_1, \rho_2), \rho_3) + A(\rho_2, A(\rho_1, \rho_3))$$

for all $\rho_1, \rho_2, \rho_3 \in \mathcal{X}(M) \oplus \Omega^1(M)$ and all m -manifolds M .

Of course, in the case of skew-symmetric bilinear A the Leibniz rule is equivalent to the Jacobi identity $\sum_{\text{cycl}(\rho_1, \rho_2, \rho_3)} A(\rho_1, A(A(\rho_2, \rho_3))) = 0$.

Example 2.6. The (not skew-symmetric) Courant bracket given by

$$\begin{aligned}
 & [X^1 \oplus \omega^1, X^2 \oplus \omega^2]_0 \\
 & := [X^1, X^2] \oplus (\mathcal{L}_{X^1}\omega^2 - i_{X^2}d\omega^1),
 \end{aligned}$$

where $X^i \oplus \omega^i \in \mathcal{X}(M) \oplus \Omega^1(M)$, satisfies the Leibniz rule, see [7, 8].

The Courant bracket $[-, -]^C$ from Example 2.2 does not satisfy the Leibniz rule.

Theorem 2.7 [2]. *If $m \geq 2$, any $\mathcal{M}f_m$ -natural bilinear operator A in the sense of Definition 2.1 satisfying the Leibniz rule is one of the following ones:*

$$\begin{aligned}
 A^{(1,a)}(\rho^1, \rho^2) &= a[X^1, X^2] \oplus 0, \\
 A^{(2,a)}(\rho^1, \rho^2) &= a[X^1, X^2] \oplus (a(\mathcal{L}_{X^1}\omega^2 - \mathcal{L}_{X^2}\omega^1)), \\
 A^{(3,a)}(\rho^1, \rho^2) &= a[X^1, X^2] \oplus a\mathcal{L}_{X^1}\omega^2, \\
 A^{(4,a,0)}(\rho^1, \rho^2) &= a[X^1, X^2] \oplus (a(\mathcal{L}_{X^1}\omega^2 - i_{X^2}d\omega^1)),
 \end{aligned}$$

where a is an arbitrary real number, and where $\rho^1 = X^1 \oplus \omega^1$ and $\rho^2 = X^2 \oplus \omega^2$.

Corollary 2.8. *If $m \geq 2$, the Courant bracket $[-, -]_0$ from Example 2.6 for m -manifolds M is the unique $\mathcal{M}f_m$ -natural bilinear operator A in the sense of Definition 2.1 satisfying the conditions:*

- (A1) $A(\rho_1, A(\rho_2, \rho_3)) = A(A(\rho_1, \rho_2), \rho_3) + A(\rho_2, A(\rho_1, \rho_3))$,
- (A2) $\pi A(\rho_1, \rho_2) = [\pi\rho_1, \pi\rho_2]$,
- (A3) $A(\rho_1, \rho_1) = i_0d\langle \rho_1, \rho_1 \rangle_+$,

for all $\rho_1, \rho_2, \rho_3 \in \mathcal{X}(M) \oplus \Omega^1(M)$ and all m -manifolds M , where $\langle -, - \rangle_+$ is the pairing of Example 2.2, $\pi : TM \oplus T^*M \rightarrow TM$ is the fibred projection given by $\pi(v, \omega) = v$ and $i_0 : T^*M \rightarrow TM \oplus T^*M$ is the fibred embedding $i_0(\omega) = (0, \omega)$.

Consequently, if $m \geq 2$, then a $\mathcal{M}f_m$ -natural bilinear operator A in the sense of Definition 2.1 satisfying the conditions (A1)–(A3) satisfies the conditions:

- (A4) $\pi\rho_1 \langle \rho_2, \rho_3 \rangle_+ = \langle A(\rho_1, \rho_2), \rho_3 \rangle_+ + \langle \rho_2, A(\rho_1, \rho_3) \rangle_+$,
- (A5) $A(\rho_1, f\rho_2) = \pi\rho_1(f)\rho_2 + fA(\rho_1, \rho_2)$

for all $\rho_1, \rho_2 \in \mathcal{X}(M) \oplus \Omega^1(M)$, all $f \in \mathcal{C}^\infty(M)$ and all m -manifolds M (i.e., putting $[[-, -]] := A$ we get an exact Courant algebroid $E = (TM \oplus T^*M, [[-, -]], \langle -, - \rangle_+, \pi, i_0)$ in the sense of [8] for any m -manifold M).

Proof. By Theorem 2.7, the conditions (A1) and (A2) imply that $A = A^{(1,1)}$ or $A = A^{(2,1)}$ or $A = A^{(3,1)}$ or $A = A^{(4,1,0)}$. On the other hand if $\rho_1 = X \oplus \omega$, then $i_0d\langle \rho_1, \rho_1 \rangle_+ = 0 \oplus di_X\omega$ and $A^{(1,1)}(\rho_1, \rho_1) = 0 \oplus 0$ and $A^{(2,1)}(\rho_1, \rho_1) = 0 \oplus 0$ and $A^{(3,1)}(\rho_1, \rho_1) = 0 \oplus \mathcal{L}_X\omega$ and $A^{(4,1,0)}(\rho_1, \rho_1) = 0 \oplus di_X\omega$. Then $A = A^{(4,1,0)}$. □

Corollary 2.9. *If $m \geq 2$, any $\mathcal{M}f_m$ -natural Lie algebra brackets on $\mathcal{X}(M) \oplus \Omega^1(M)$ [i.e., $\mathcal{M}f_m$ -natural skew-symmetric bilinear operator satisfying the*

Jacobi identity (Leibniz rule) is the constant multiple of the one of the following two Lie algebra brackets:

$$\begin{aligned}
 [[X^1 \oplus \omega^1, X^2 \oplus \omega^2]]_1 &= [X^1, X^2] \oplus 0, \\
 [[X^1 \oplus \omega^1, X^2 \oplus \omega^2]]_2 &= [X^1, X^2] \oplus (\mathcal{L}_{X^1}\omega^2 - \mathcal{L}_{X^2}\omega^1).
 \end{aligned}$$

At the end of this section we are going to describe completely all Lie algebroids $(TM \otimes T^*M, [[-, -]], a)$ which are invariant with respect to immersions ($\mathcal{M}f_m$ -maps). The concept of Lie algebroids can be found in the fundamental book [6].

Of course, the anchor $a : TM \oplus T^*M \rightarrow TM$ for all m -manifolds M must be $\mathcal{M}f_m$ -natural transformation [i.e., $Tf \circ a = a \circ (Tf \oplus T^*f)$ for any $\mathcal{M}f_m$ -map $f : M \rightarrow M^1$] and fibre linear. By Corollary 2.9, $[[-, -]] = \mu[[-, -]]_1$ or $[[-, -]] = \mu[[-, -]]_2$ for some $\mu \in \mathbf{R}$.

Lemma 2.10. *Any $\mathcal{M}f_m$ -natural transformation $a : TM \oplus T^*M \rightarrow TM$ which is fibre linear is the constant multiple of the fibre projection $\pi : TM \oplus T^*M \rightarrow TM$.*

Proof. Clearly, a is determined by the values $\langle \eta, a_x(v, \omega) \rangle \in \mathbf{R}$ for all $\omega, \eta \in T_x^*M, v \in T_xM, x \in M, M \in \text{Obj}(\mathcal{M}f_m)$. By the standard chart arguments, we may assume $M = \mathbf{R}^m, x = 0, \eta = d_0x^1$. We can write $\langle d_0x^1, a_0(v, \omega) \rangle = \sum_i \alpha_i v^i + \sum_j \beta^j \omega_j$, where v^i are the coordinates of v and ω_j are the coordinates of ω , and where α_i and β^j are the real numbers determined by a_0 . Then using the invariance of a_0 with respect to the maps $(\tau^1 x^1, \dots, \tau^m x^m)$ for $\tau^1 > 0, \dots, \tau^m > 0$ we deduce that $\alpha_2 = \dots = \alpha_m = 0$ and $\beta_1 = \dots = \beta_m = 0$. Then the vector space of all a in question is at most 1-dimensional. Thus the dimension argument completes the proof. \square

So, $a = k\pi$ for some real number k . It must be $a([[X^1 \oplus 0, X^2 \oplus 0]]) = [a(X^1 \oplus 0), a(X^2 \oplus 0)]$ for any vector fields X^1 and X^2 on M . This gives the condition $k\mu[X^1, X^2] = k^2[X^1, X^2]$. Then $k\mu = k^2$, and then ($k = 0$ and μ arbitrary) or ($k \neq 0$ and $\mu = k$). Consider two cases:

1. $[[-, -]] = \mu[[-, -]]_1$. Let $\rho^1 = X^1 \oplus \omega^1$ and $\rho^2 = X^2 \oplus \omega^2$. It must be $[[\rho^1, f\rho^2]] = a(\rho^1)(f)\rho^2 + f[[\rho^1, \rho^2]]$. Considering the $\Omega^1(M)$ -parts of both sides of this equality we get $0 = kX^1(f)\omega^2 + 0$ for any vector fields X^1, X^2 on M any map $f : M \rightarrow \mathbf{R}$ and any $\omega^1, \omega^2 \in \Omega^1(M)$. Then $k = 0$. Then considering the $\mathcal{X}(M)$ -parts we get $\mu[X^1, fX^2] = f\mu[X^1, X^2]$. Then $\mu X^1(f)X^2 = 0$ for all vector fields X^1 and X^2 on M and all maps $f : M \rightarrow \mathbf{R}$, i.e., $\mu = 0$.

2. $[[-, -]] = \mu[[-, -]]_2$. Let $\rho^1 = 0 \oplus \omega^1$ and $\rho^2 = X^2 \oplus 0$. It must be $[[\rho^1, f\rho^2]] = a(\rho^1)(f)\rho^2 + f[[\rho^1, \rho^2]]$. Considering the $\Omega^1(M)$ -parts of both sides of this equality we get $-\mu\mathcal{L}_{fX^2}\omega^1 = -\mu f\mathcal{L}_{X^2}\omega^1$. Then $\mu = 0$ or $d i_{fX^2}\omega^1 + i_{fX^2}d\omega^1 = f d i_{X^2}\omega^1 + f i_{X^2}d\omega^1$. Putting $\omega^1 = dg$ we get $\mu = 0$ or $d(i_{fX^2}dg) = f d i_{X^2}dg$. Then $\mu = 0$ or $d(fX^2g) = fd(X^2g)$. Then $\mu = 0$ or $X^2(g)df = 0$ for any X^2, g, f in question. Putting $X^2 = \frac{\partial}{\partial x^1}$ and $f = g = x^1$ we get $\mu = 0$ or $dx^1 = 0$. Then $\mu = 0$, and then $k = \mu = 0$.

On the other hand one can directly show that $(TM \oplus T^*M, 0[[-, -]]_1, 0\pi)$ is a Lie algebroid. Thus we have

Proposition 2.11. *If $m \geq 2$, $(TM \otimes T^*M, 0, 0)$ is the only invariant with respect to $\mathcal{M}f_m$ -maps Lie algebroid $(EM, [[-, -]], a)$ with $EM = TM \oplus T^*M$.*

3. The Natural Operators Similar to the Twisted Courant Bracket

Definition 3.1. A $\mathcal{M}f_m$ -natural operator A sending p -forms $H \in \Omega^p(M)$ on m -manifolds M into bilinear operators

$$A_H : (\mathcal{X}(M) \oplus \Omega^1(M)) \times (\mathcal{X}(M) \oplus \Omega^1(M)) \rightarrow \mathcal{X}(M) \oplus \Omega^1(M),$$

is a $\mathcal{M}f_m$ -invariant family of regular operators (functions)

$$A : \Omega^p(M) \rightarrow \text{Lin}_2((\mathcal{X}(M) \oplus \Omega^1(M)) \times (\mathcal{X}(M) \oplus \Omega^1(M)), \mathcal{X}(M) \oplus \Omega^1(M))$$

for all m -manifolds M , where $\text{Lin}_2(U \times V, W)$ denotes the vector space of all bilinear (over \mathbf{R}) functions $U \times V \rightarrow W$ for any real vector spaces U, V, W .

The $\mathcal{M}f_m$ -invariance of A means that if $H^1 \in \Omega^p(M)$ and $H^2 \in \Omega^p(\overline{M})$ are φ -related and $(X^1 \oplus \omega^1, X^2 \oplus \omega^2)$ and $(\overline{X}^1 \oplus \overline{\omega}^1, \overline{X}^2 \oplus \overline{\omega}^2)$ are φ -related by an $\mathcal{M}f_m$ -map $\varphi : M \rightarrow \overline{M}$, then so are $A_{H^1}(X^1 \oplus \omega^1, X^2 \oplus \omega^2)$ and $A_{H^2}(\overline{X}^1 \oplus \overline{\omega}^1, \overline{X}^2 \oplus \overline{\omega}^2)$.

The regularity of A means that it transforms smoothly parametrized families $(H_t, X_t^1 \oplus \omega_t^1, X_t^2 \oplus \omega_t^2)$ into smoothly parametrized families $A_{H_t}(X_t^1 \oplus \omega_t^1, X_t^2 \oplus \omega_t^2)$.

Example 3.2. The most important example of $\mathcal{M}f_m$ -natural operator in the sense of Definition 3.1 for $p = 3$ is given by the H -twisted Courant bracket

$$[X^1 \oplus \omega^1, X^2 \oplus \omega^2]_H := [X^1, X^2] \oplus (\mathcal{L}_{X^1}\omega^2 - i_{X^2}d\omega^1 + i_{X^1}i_{X^2}H)$$

for all 3-forms $H \in \Omega^3(M)$ and all m -manifolds M . We call this $\mathcal{M}f_m$ -natural operator the twisted Courant bracket $\mathcal{M}f_m$ -natural operator.

Example 3.3. The operator given by $[-, -]_{dH}$ for all $H \in \Omega^2(M)$ and all m -manifolds M is a $\mathcal{M}f_m$ -natural operator in the sense of Definition 3.1 for $p = 2$.

The main result of this section is the following

Theorem 3.4. *Assume $m \geq 3$. Then we have:*

1. Any $\mathcal{M}f_m$ -natural operator A in the sense of Definition 3.1 for $p = 2$ such that $A_H = A_{H+dH^1}$ for any $H \in \Omega^2(M)$ and any $H^1 \in \Omega^1(M)$ is of the form

$$A_H(\rho^1, \rho^2) = a[X^1, X^2] \oplus (b_1\mathcal{L}_{X^2}\omega^1 + b_2\mathcal{L}_{X^1}\omega^2 + b_3d\langle \rho^1, \rho^2 \rangle_+ + b_4d\langle \rho^1, \rho^2 \rangle_- + ci_{X^1}i_{X^2}dH),$$

for (uniquely determined by A) reals a, b_1, \dots, c , where 2-forms $H \in \Omega^2(M)$, pairs $\rho^i = X^i \oplus \omega^i \in \mathcal{X}(M) \oplus \Omega^1(M)$ for $i = 1, 2$ and m -manifolds M are arbitrary.

2. Any $\mathcal{M}f_m$ -natural operator (not necessarily satisfying $A_H = A_{H+dH^1}$) in the sense of Definition 3.1 for $p = 3$ is of the form

$$A_H(\rho^1, \rho^2) = a[X^1, X^2] \oplus \left(b_1 \mathcal{L}_{X^2} \omega^1 + b_2 \mathcal{L}_{X^1} \omega^2 + b_3 d \langle \rho^1, \rho^2 \rangle_+ + b_4 d \langle \rho^1, \rho^2 \rangle_- + c i_{X^1} i_{X^2} H \right),$$

for (uniquely determined by A) reals a, b_1, \dots, c , where 3-forms $H \in \Omega^3(M)$, pairs $\rho^i = X^i \oplus \omega^i \in \mathcal{X}(M) \oplus \Omega^1(M)$ for $i = 1, 2$ and m -manifolds M are arbitrary.

3. If $p \geq 4$, any $\mathcal{M}f_m$ -natural operator (not necessarily satisfying $A_H = A_{H+dH^1}$) in the sense of Definition 3.1 is of the form

$$A_H(\rho^1, \rho^2) = a[X^1, X^2] \oplus \left(b_1 \mathcal{L}_{X^2} \omega^1 + b_2 \mathcal{L}_{X^1} \omega^2 + b_3 d \langle \rho^1, \rho^2 \rangle_+ + b_4 d \langle \rho^1, \rho^2 \rangle_- \right)$$

for (uniquely determined by A) reals a, b_1, \dots, b_4 , where p -forms $H \in \Omega^p(M)$, pairs $\rho^i = X^i \oplus \omega^i \in \mathcal{X}(M) \oplus \Omega^1(M)$ for $i = 1, 2$ and m -manifolds M are arbitrary.

Proof. Clearly, A_0 , where 0 is the zero p -form, can be treated as the bilinear operator in the sense of Definition 2.1. Then A_0 is described in Theorem 2.3. So we can replace A by $A - A_0$. In other words, we have assumption $A_0 = 0$.

By the invariance, A is determined by the values $A_H(X^1 \oplus \omega^1, X^2 \oplus \omega^2)|_0$ for all $H \in \Omega^p(\mathbf{R}^m)$, $X^i \oplus \omega^i \in \mathcal{X}(\mathbf{R}^m) \oplus \Omega^1(\mathbf{R}^m)$. Put

$$A_H(X^1 \oplus \omega^1, X^2 \oplus \omega^2)|_0 = (A_H^1(X^1 \oplus \omega^1, X^2 \oplus \omega^2)|_0, A_H^2(X^1 \oplus \omega^1, X^2 \oplus \omega^2)|_0),$$

where $A_H^1(\dots)|_0 \in T_0 \mathbf{R}^m$ and $A_H^2(\dots)|_0 \in T^* \mathbf{R}^m$. Then A is determined by

$$\langle A_H^1(X^1 \oplus \omega^1, X^2 \oplus \omega^2)|_0, \eta \rangle \in \mathbf{R} \text{ and } \langle A_H^2(X^1 \oplus \omega^1, X^2 \oplus \omega^2)|_0, \mu \rangle \in \mathbf{R}$$

for all $H \in \Omega^p(\mathbf{R}^m)$, $X^i \oplus \omega^i \in \mathcal{X}(\mathbf{R}^m) \oplus \Omega^1(\mathbf{R}^m)$, $\eta \in T_0^* \mathbf{R}^m$, $\mu \in T_0 \mathbf{R}^m$, $i = 1, 2$.

By the non-linear Peetre theorem, see [5], A is of finite order. It means that there is a finite number r such that from $(j_x^r H = j_x^r \bar{H}, j_x^r(\rho^i) = j_x^r(\bar{\rho}^i), i = 1, 2)$ it follows $A_H(\rho^1, \rho^2)|_x = A_{\bar{H}}(\bar{\rho}^1, \bar{\rho}^2)|_x$. So, we may assume that $H, X^1, X^2, \omega^1, \omega^2$ are polynomials of degree not more than r .

Using the invariance of A with respect to the homotheties and the bilinearity of A_H (for given H) we obtain homogeneity condition

$$\begin{aligned} & \left\langle A_{\left(\frac{1}{t} \text{id}\right)_* H} \left(t \left(\frac{1}{t} \text{id}\right)_* X^1 \oplus t \left(\frac{1}{t} \text{id}\right)_* \omega^1, t \left(\frac{1}{t} \text{id}\right)_* X^2 \right. \right. \\ & \quad \left. \left. \oplus t \left(\frac{1}{t} \text{id}\right)_* \omega^2 \right)|_0, \eta \right\rangle \\ & = t \langle A_H^1(X^1 \oplus \omega^1, X^2 \oplus \omega^2)|_0, \eta \rangle. \end{aligned}$$

Then, by the homogeneous function theorem, since A is of finite order and regular and $A_0 = 0$ and $p \geq 2$, we have $\langle A_H^1(X^1 \oplus \omega^1, X^2 \oplus \omega^2)|_0, \eta \rangle = 0$.

Using the same arguments we get homogeneity condition

$$\begin{aligned} & \left\langle A_H^2 \left(t \left(\frac{1}{t} \text{id} \right)_* X^1 \oplus t \left(\frac{1}{t} \text{id} \right)_* \omega^1, t \left(\frac{1}{t} \text{id} \right)_* X^2 \right. \right. \\ & \quad \left. \left. \oplus t \left(\frac{1}{t} \text{id} \right)_* \omega^2 \right)_{|_0}, \mu \right\rangle \\ & = t^3 \langle A_H^2(X^1 \oplus \omega^1, X^2 \oplus \omega^2)_{|_0}, \mu \rangle. \end{aligned}$$

Then, if $p = 2$, by the homogeneous function theorem and the bilinearity of A_H and the assumptions $A_0 = 0$ and $A_H = A_{H+dH^1}$, the value $\langle A_H^2(X^1 \oplus \omega^1, X^2 \oplus \omega^2)_{|_0}, \mu \rangle$ depends quadrilinearly on $X^1_{|_0}, X^2_{|_0}, j_0^1(H - H|_0)$ and μ , only. By $m \geq 3$ and the regularity of A , we may assume that $X^1_{|_0}, X^2_{|_0}$ and μ are linearly independent. Then by the invariance we may assume $X^1_{|_0} = \partial_{1|_0}, X^2_{|_0} = \partial_{2|_0}$ and $\mu = \partial_{3|_0}$. Then A is determined by the values $\langle A_{x^{i_1} dx^{i_2} \wedge dx^{i_3}}^2(\partial_1 \oplus 0, \partial_2 \oplus 0), \partial_{3|_0} \rangle$ for all $i_1 = 1, \dots, m$ and i_2, i_3 with $1 \leq i_2 < i_3 \leq m$. Then using the invariance of A with respect to τid for $\tau^i > 0$ we deduce that only $v := \langle A_{x^1 dx^2 \wedge dx^3}^2(\partial_1 \oplus 0, \partial_2 \oplus 0), \partial_{3|_0} \rangle, w := \langle A_{x^2 dx^1 \wedge dx^3}^2(\partial_1 \oplus 0, \partial_2 \oplus 0), \partial_{3|_0} \rangle, z := \langle A_{x^3 dx^1 \wedge dx^2}^2(\partial_1 \oplus 0, \partial_2 \oplus 0), \partial_{3|_0} \rangle$ may be not-zero. But $x^1 dx^2 \wedge dx^3 = -x^2 dx^1 \wedge dx^3 + d(\dots)$. So, $v = -w$. Similarly, $v = -z$. Therefore the vector space of all A in question with $A_0 = 0$ and $A_H = A_{H+dH^1}$ is at most one-dimensional. The part (1) of the theorem is complete. If $p = 3$, then (by almost the same arguments as for $p = 2$) A is determined by the values $\langle A_{dx^{i_1} \wedge dx^{i_2} \wedge dx^{i_3}}^2(\partial_1 \oplus 0, \partial_2 \oplus 0), \partial_{3|_0} \rangle \in \mathbf{R}$ for all i_1, i_2, i_3 with $1 \leq i_1 < i_2 < i_3 \leq m$. Then using the invariance with respect to $(\tau^1 x^1, \dots, \tau^m x^m)$ for $\tau^i > 0$ we deduce that only the value $\langle A_{dx^1 \wedge dx^2 \wedge dx^3}^2(\partial_1 \oplus 0, \partial_2 \oplus 0), \partial_{3|_0} \rangle \in \mathbf{R}$ may be not-zero. Therefore the vector space of all A in question with $A_0 = 0$ is one-dimensional (generated by the natural operator $0 \oplus i_{X^1} i_{X^2} H$).

If $p \geq 4$, then (similarly as for $p = 2$) $\langle A_H^2(X^1 \oplus \omega^1, X^2 \oplus \omega^2)_{|_0}, \mu \rangle = 0$. Theorem 3.4 is complete. □

Corollary 3.5. *If $m \geq 3$, any $\mathcal{M}f_m$ -natural operator A in the sense of Definition 3.1 for $p = 3$ such that A_H is skew-symmetric for any $H \in \Omega^3(M)$ and any m -manifold M is of the form*

$$\begin{aligned} A_H(X^1 \oplus \omega^1, X^2 \oplus \omega^2) &= a[X^1, X^2] \\ &\oplus \left(b(\mathcal{L}_{X^1} \omega^2 - \mathcal{L}_{X^2} \omega^1) + cd \langle X^2 \oplus \omega^1, X^1 \oplus \omega^2 \rangle_- + ei_{X^1} i_{X^2} H \right) \end{aligned}$$

for (uniquely determined by A) real numbers a, b, c, e .

Roughly speaking, Corollary 3.5 says that any $\mathcal{M}f_m$ -natural operator A in the sense of Definition 3.1 such that A_H is skew-symmetric for any $H \in \Omega^3(M)$ and any m -manifold M coincides with the “skew-symmetrization” of the twisted Courant bracket $\mathcal{M}f_m$ -natural operator up to four real constants a, b, c, e .

Corollary 3.6. *If $m \geq 3$, then the twisted Courant bracket $\mathcal{M}f_m$ -natural operator from Example 3.2 is the unique $\mathcal{M}f_m$ -natural operator A in the sense of Definition 3.1 for $p = 3$ satisfying the following properties:*

(B1) $A_0(\rho_1, \rho_2) = [\rho_1, \rho_2]_0,$

(B2) $A_H(X \oplus 0, Y \oplus 0) = [X, Y] \oplus i_X i_Y H$

for all closed $H \in \Omega_{cl}^3(M)$, all $\rho_1, \rho_2, X \oplus 0, Y \oplus 0 \in \mathcal{X}(M) \oplus \Omega^1(M)$ and all m -manifolds M , where $[-, -]_0$ is the $\mathcal{M}f_m$ -natural bilinear operator given by the (not skew-symmetric) Courant bracket as in Example 2.6.

Proof. Clearly, the twisted Courant bracket $\mathcal{M}f_m$ -natural operator satisfies (B1) and (B2). Consider A in question satisfying (B1) and (B2). Then by Theorem 3.4, there exist uniquely determined reals a, b_1, \dots, c such that for all $H \in \Omega^3(M)$ and m -manifolds M

$$A_H(\rho^1, \rho^2) = a[X^1, X^2]$$

$$\oplus \left(b_1 \mathcal{L}_{X^2} \omega^1 + b_2 \mathcal{L}_{X^1} \omega^2 + b_3 d \langle \rho^1, \rho^2 \rangle_+ + b_4 d \langle \rho^1, \rho^2 \rangle_- + ci_{X^1} i_{X^2} H \right),$$

where $\rho^i = X^i \oplus \omega^i \in \mathcal{X}(M) \oplus \Omega^1(M)$ are arbitrary. Putting $\omega^1 = \omega^2 = 0$ we get $A_H(\rho^1, \rho^2) = a[X^1, X^2] \oplus ci_{X^1} i_{X^2} H$. Then condition (B2) implies $c = 1$. Putting $H = 0$ we get

$$A_0(\rho^1, \rho^2) = a[X^1, X^2] \oplus \left(b_1 \mathcal{L}_{X^2} \omega^1 + b_2 \mathcal{L}_{X^1} \omega^2 + b_3 d \langle \rho^1, \rho^2 \rangle_+ + b_4 d \langle \rho^1, \rho^2 \rangle_- \right)$$

for all $\rho^i = X^i \oplus \omega^i \in \mathcal{X}(M) \oplus \Omega^1(M)$ and all m -manifolds M . But A_0 is a $\mathcal{M}f_m$ -natural bilinear operator in the sense of Definition 2.1. Then a, b_1, b_2, b_3, b_4 are uniquely determined because of Theorem 2.3. Then a, b_1, \dots, c are uniquely determined. So, A is uniquely determined by conditions (B1) and (B2). □

4. The Natural Operators Similar to the Twisted Courant Bracket and Defined for Closed p -Forms Only

In the previous section, we considered $\mathcal{M}f_m$ -natural operators A which are defined for all p -forms H . In this section, we observe what happens if A are defined for closed p -forms H , only. We start with the following

Definition 4.1. A $\mathcal{M}f_m$ -natural operator A sending closed p -forms $H \in \Omega_{cl}^p(M)$ on m -manifolds M into bilinear operators

$$A_H : (\mathcal{X}(M) \oplus \Omega^1(M)) \times (\mathcal{X}(M) \oplus \Omega^1(M)) \rightarrow \mathcal{X}(M) \oplus \Omega^1(M),$$

is a $\mathcal{M}f_m$ -invariant family of regular operators (functions)

$$A : \Omega_{cl}^p(M) \rightarrow Lin_2((\mathcal{X}(M) \oplus \Omega^1(M)) \times (\mathcal{X}(M) \oplus \Omega^1(M)), \mathcal{X}(M) \oplus \Omega^1(M)),$$

for all m -manifolds M .

We have the following corollary of Theorem 3.4.

Corollary 4.2. Assume $m \geq 3$. Then we have:

1. If $p = 3$, any $\mathcal{M}f_m$ -natural operator in the sense of Definition 4.1 is of the form

$$A_H(\rho^1, \rho^2) = a[X^1, X^2] \oplus (b_1 \mathcal{L}_{X^2} \omega^1 + b_2 \mathcal{L}_{X^1} \omega^2 + b_3 d \langle \rho^1, \rho^2 \rangle_+ + b_4 d \langle \rho^1, \rho^2 \rangle_- + ci_{X^1} i_{X^2} H),$$

for uniquely determined by A reals a, b_1, \dots, c , where closed 3-forms $H \in \Omega_{cl}^3(M)$, pairs $\rho^i = X^i \oplus \omega^i \in \mathcal{X}(M) \oplus \Omega^1(M)$ for $i = 1, 2$ and m -manifolds M are arbitrary.

2. If $p \geq 4$, any $\mathcal{M}f_m$ -natural operator in the sense of Definition 4.1 is of the form

$$A_H(\rho^1, \rho^2) = a[X^1, X^2] \oplus \left(b_1 \mathcal{L}_{X^2} \omega^1 + b_2 \mathcal{L}_{X^1} \omega^2 + b_3 d \langle \rho^1, \rho^2 \rangle_+ + b_4 d \langle \rho^1, \rho^2 \rangle_- \right)$$

for uniquely determined by A reals a, b_1, \dots, b_4 , where closed p -forms $H \in \Omega_{cl}^p(M)$, pairs $\rho^i = X^i \oplus \omega^i$ for $i = 1, 2$ and m -manifolds M are arbitrary.

Proof. Let A be a $\mathcal{M}f_m$ -natural operator in the sense of Definition 4.1 for p . Define a $\mathcal{M}f_m$ -natural operator A^1 in the sense of Definition 3.1 for $p - 1$ by $A^1_{\tilde{H}} = A_{d\tilde{H}}$. Then $A^1_{\tilde{H}+dH_1} = A^1_{\tilde{H}}$ for any $\tilde{H} \in \Omega^{p-1}(M)$ and $H_1 \in \Omega^{p-2}(M)$.

If $p = 3$, then by Theorem 3.4, A^1 is of the form

$$A^1_{\tilde{H}}(\rho^1, \rho^2) = a[X^1, X^2] \oplus \left(b_1 \mathcal{L}_{X^2} \omega^1 + b_2 \mathcal{L}_{X^1} \omega^2 + b_3 d \langle \rho^1, \rho^2 \rangle_+ + b_4 d \langle \rho^1, \rho^2 \rangle_- + ci_{X^1} i_{X^2} d\tilde{H} \right)$$

for uniquely determined reals a, b_1, \dots, c and all $\tilde{H} \in \Omega^2(M)$, where $\rho^i = X^i \oplus \omega^i$ for $i = 1, 2$. Then

$$A_H(\rho^1, \rho^2) = a[X^1, X^2] \oplus \left(b_1 \mathcal{L}_{X^2} \omega^1 + b_2 \mathcal{L}_{X^1} \omega^2 + b_3 d \langle \rho^1, \rho^2 \rangle_+ + b_4 d \langle \rho^1, \rho^2 \rangle_- + ci_{X^1} i_{X^2} H \right)$$

for all exact 3-forms H , where $\rho^i = X^i \oplus \omega^i$ for $i = 1, 2$. But by the locality of A and the Poincare lemma we may replace the phrase “all exact 3-forms” by “all closed 3-forms”.

If $p \geq 4$, then by Theorem 3.4, A^1 is of the form

$$A^1_{\tilde{H}}(\rho^1, \rho^2) = a[X^1, X^2] \oplus \left(b_1 \mathcal{L}_{X^2} \omega^1 + b_2 \mathcal{L}_{X^1} \omega^2 + b_3 d \langle \rho^1, \rho^2 \rangle_+ + b_4 d \langle \rho^1, \rho^2 \rangle_- + ci_{X^1} i_{X^2} d\tilde{H} \right)$$

for uniquely determined reals a, b_1, \dots, c (with arbitrary c if $p = 4$ and with $c = 0$ if $p \geq 5$) and all $\tilde{H} \in \Omega^{p-1}(M)$, where $\rho^i = X^i \oplus \omega^i$ for $i = 1, 2$. The condition $A^1_{\tilde{H}} = A^1_{\tilde{H}+dH_1}$ implies $ci_{X^1} i_{X^2} dH_1 = 0$ for any $H_1 \in \Omega^{p-2}(M)$. If $p = 4$, putting $X^1 = \partial_1, X^2 = \partial_2$ and $H_1 = x^1 dx^2 \wedge dx^3$, we get $c(-dx^3) = 0$, i.e., $c = 0$. If $p \geq 5$, then $c = 0$, see above. Next, we proceed similarly as in the case $p = 3$. □

The above corollary and Theorem 3.4 imply

Theorem 4.3. *If $m \geq 3$ and $p \geq 3$ then any $\mathcal{M}f_m$ -natural operator in the sense of Definition 4.1 can be extended uniquely to a $\mathcal{M}f_m$ -natural operator in the sense of Definition 3.1.*

Roughly speaking, if $m \geq 3$ and $p \geq 3$, then any $\mathcal{M}f_m$ -natural operator in the sense of Definition 4.1 can be treated as the $\mathcal{M}f_m$ -natural operator in the sense of Definition 3.1, and vice-versa.

5. The Natural Operators Similar to the Twisted Courant Bracket and Satisfying the Leibniz Rule for Closed 3-Forms

Definition 5.1. A $\mathcal{M}f_m$ -natural operator A in the sense of Definition 3.1 (or equivalently in the sense of Definition 4.1) satisfies the Leibniz rule for closed p -forms if

$$A_H(\rho_1, A_H(\rho_2, \rho_3)) = A_H(A_H(\rho_1, \rho_2), \rho_3) + A_H(\rho_2, A_H(\rho_1, \rho_3))$$

for all $\rho_1, \rho_2, \rho_3 \in \mathcal{X}(M) \oplus \Omega^1(M)$, all closed p -forms $H \in \Omega_{cl}^p(M)$ and all m -manifolds M .

Example 5.2. The twisted Courant bracket $\mathcal{M}f_m$ -natural operator presented in Example 3.2 satisfies the Leibniz rule for closed 3-forms, see [3, 8].

Theorem 5.3. *If $m \geq 3$, any $\mathcal{M}f_m$ -natural operator A in the sense of Definition 3.1 (or equivalently of Definition 4.1) for $p = 3$ satisfying the Leibniz rule for closed 3-forms is one of the $\mathcal{M}f_m$ -natural operators:*

$$\begin{aligned} A_H^{(1,a)}(\rho_1, \rho_2) &= a[X^1, X^2] \oplus 0, \\ A_H^{(2,a)}(\rho^1, \rho^2) &= a[X^1, X^2] \oplus (a(\mathcal{L}_{X^1}\omega^2 - \mathcal{L}_{X^2}\omega^1)), \\ A_H^{(3,a)}(\rho^1, \rho^2) &= a[X^1, X^2] \oplus (a\mathcal{L}_{X^1}\omega^2), \\ A_H^{(4,a,e)}(\rho^1, \rho^2) &= a[X^1, X^2] \oplus (a(\mathcal{L}_{X^1}\omega^2 - i_{X^2}d\omega^1) + ei_{X^1}i_{X^2}H), \end{aligned}$$

where $\rho^1 = X^1 \oplus \omega^1$ and $\rho^2 = X^2 \oplus \omega^2$, and a and e are arbitrary real numbers.

Proof. Let A be a $\mathcal{M}f_m$ -natural operator in the sense of Definition 3.1 for $p = 3$ such that A_H satisfies the Leibniz rule for any closed $H \in \Omega_{cl}^3(M)$. By Theorem 3.4, A is of the form

$$\begin{aligned} A_H(X^1 \oplus \omega^1, X^2 \oplus \omega^2) &= a[X^1, X^2] \\ &\oplus (b_1\mathcal{L}_{X^2}\omega^1 + b_2\mathcal{L}_{X^1}\omega^2 + c_1di_{X^2}\omega^1 + c_2di_{X^1}\omega^2 + ei_{X^1}i_{X^2}H), \end{aligned}$$

for (uniquely determined by A) real numbers a, b_1, b_2, c_1, c_2, e . Then for any $X^1, X^2, X^3 \in \mathcal{X}(M)$ and $\omega^1, \omega^2, \omega^3 \in \Omega^1(M)$ we have

$$\begin{aligned} A_H(X^1 \oplus \omega^1, A_H(X^2 \oplus \omega^2, X^3 \oplus \omega^3)) &= a^2[X^1, [X^2, X^3]] \oplus \Omega, \\ A_H(A_H(X^1 \oplus \omega^1, X^2 \oplus \omega^2), X^3 \oplus \omega^3) &= a^2[[X^1, X^2], X^3] \oplus \Theta, \\ A_H(X^2 \oplus \omega^2, A_H(X^1 \oplus \omega^1, X^3 \oplus \omega^3)) &= a^2[X^2, [X^1, X^3]] \oplus \mathcal{T}, \end{aligned}$$

where

$$\begin{aligned} \Omega &= b_1\mathcal{L}_a[X^2, X^3]\omega^1 + c_1di_a[X^2, X^3]\omega^1 + ei_{X^1}i_a[X^2, X^3]H \\ &\quad + b_2\mathcal{L}_{X^1}(b_1\mathcal{L}_{X^3}\omega^2 + b_2\mathcal{L}_{X^2}\omega^3 + c_1di_{X^3}\omega^2 + c_2di_{X^2}\omega^3 + ei_{X^2}i_{X^3}H) \\ &\quad + c_2di_{X^1}(b_1\mathcal{L}_{X^3}\omega^2 + b_2\mathcal{L}_{X^2}\omega^3 + c_1di_{X^3}\omega^2 + c_2di_{X^2}\omega^3 + ei_{X^2}i_{X^3}H), \\ \Theta &= b_2\mathcal{L}_a[X^1, X^2]\omega^3 + c_2di_a[X^1, X^2]\omega^3 + ei_a[X^1, X^2]i_{X^3}H \\ &\quad + b_1\mathcal{L}_{X^3}(b_1\mathcal{L}_{X^2}\omega^1 + b_2\mathcal{L}_{X^1}\omega^2 + c_1di_{X^2}\omega^1 + c_2di_{X^1}\omega^2 + e_{X^1}i_{X^2}H) \\ &\quad + c_1di_{X^3}(b_1\mathcal{L}_{X^2}\omega^1 + b_2\mathcal{L}_{X^1}\omega^2 + c_1di_{X^2}\omega^1 + c_2di_{X^1}\omega^2 + ei_{X^1}i_{X^2}H), \\ \mathcal{T} &= b_1\mathcal{L}_a[X^1, X^3]\omega^2 + c_1di_a[X^1, X^3]\omega^2 + ei_{X^2}i_a[X^1, X^3]H \\ &\quad + b_2\mathcal{L}_{X^2}(b_1\mathcal{L}_{X^3}\omega^1 + b_2\mathcal{L}_{X^1}\omega^3 + c_1di_{X^3}\omega^1 + c_2di_{X^1}\omega^3 + ei_{X^1}i_{X^3}H) \\ &\quad + c_2di_{X^2}(b_1\mathcal{L}_{X^3}\omega^1 + b_2\mathcal{L}_{X^1}\omega^3 + c_1di_{X^3}\omega^1 + c_2di_{X^1}\omega^3 + ei_{X^1}i_{X^3}H). \end{aligned}$$

The Leibniz rule of A_H is equivalent to $\Omega = \Theta + \mathcal{T}$.

Putting $H = 0$, we are in the situation of Theorem 2.7. Then by Theorem 2.7 (i.e., by Theorem 3.2 in [2]) we get $(b_1, b_2, c_1, c_2) = (0, 0, 0, 0)$ or $(b_1, b_2, c_1, c_2) = (0, a, 0, 0)$ or $(b_1, b_2, c_1, c_2) = (-a, a, 0, 0)$ or $(b_1, b_2, c_1, c_2) = (-a, a, a, 0)$. More, A_0 for such (b_1, b_2, c_1, c_2) satisfies the Leibniz rule.

Therefore (as $c_2 = 0$) the Leibniz rule of A_H is equivalent to the equality

$$\begin{aligned} &eai_{X^1}i_{[X^2, X^3]}H + b_2e\mathcal{L}_{X^1}i_{X^2}i_{X^3}H \\ &= eai_{[X^1, X^2]}i_{X^3}H + b_1e\mathcal{L}_{X^3}i_{X^1}i_{X^2}H + c_1edi_{X^3}i_{X^1}i_{X^2}H \\ &\quad + eai_{X^2}i_{[X^1, X^3]}H + b_2e\mathcal{L}_{X^2}i_{X^1}i_{X^3}H. \end{aligned}$$

If $(b_1, b_2, c_1, c_2) = (0, 0, 0, 0)$, the above equality is equivalent to

$$eai_{X^1}i_{[X^2, X^3]}H = eai_{[X^1, X^2]}i_{X^3}H + eai_{X^2}i_{[X^1, X^3]}H.$$

Putting $X^1 = \partial_1$, $X^2 = \partial_1 + x^1\partial_3$ and $X^3 = \partial_2$ we have $[X^2, X^3] = 0$, $[X^1, X^3] = 0$ and $[X^1, X^2] = \partial_3$, and then $0 = eai_{\partial_3}i_{\partial_2}H$ for any closed H (for example for $H = dx^1 \wedge dx^2 \wedge dx^3$). Consequently $e = 0$ or $a = 0$.

If $(b_1, b_2, c_1, c_2) = (0, a, 0, 0)$, the above equality is equivalent to

$$\begin{aligned} &eai_{X^1}i_{[X^2, X^3]}H + ea\mathcal{L}_{X^1}i_{X^2}i_{X^3}H \\ &= eai_{[X^1, X^2]}i_{X^3}H + eai_{X^2}i_{[X^1, X^3]}H + ea\mathcal{L}_{X^2}i_{X^1}i_{X^3}H. \end{aligned}$$

Putting $X^1 = \partial_1$, $X^2 = \partial_2$ and $X^3 = \partial_3$ and $H = x^2dx^1 \wedge dx^2 \wedge dx^3$ (it is closed) we have $[X^2, X^3] = 0$, $[X^1, X^2] = 0$, $[X^1, X^3] = 0$, $\mathcal{L}_{X^2}i_{X^1}i_{X^3}H = \mathcal{L}_{\partial_2}x^2dx^2 = dx^2$ and $\mathcal{L}_{X^1}i_{X^2}i_{X^3}H = \mathcal{L}_{\partial_1}(-x^2dx^1) = 0$. Then $eadx^2 = 0$. So, $a = 0$ or $e = 0$.

If $(b_1, b_2, c_1, c_2) = (-a, a, 0, 0)$, the above equality is equivalent to

$$\begin{aligned} &eai_{X^1}i_{[X^2, X^3]}H + ea\mathcal{L}_{X^1}i_{X^2}i_{X^3}H \\ &= eai_{[X^1, X^2]}i_{X^3}H - ea\mathcal{L}_{X^3}i_{X^1}i_{X^2}H + eai_{X^2}i_{[X^1, X^3]}H + ea\mathcal{L}_{X^2}i_{X^1}i_{X^3}H. \end{aligned}$$

Putting $X^1 = \partial_1$, $X^2 = \partial_2$ and $X^3 = \partial_3$ and $H = x^2dx^1 \wedge dx^2 \wedge dx^3$ we have (see above) $[X^2, X^3] = 0$, $[X^1, X^2] = 0$, $[X^1, X^3] = 0$, $\mathcal{L}_{X^2}i_{X^1}i_{X^3}H = dx^2$, $\mathcal{L}_{X^1}i_{X^2}i_{X^3}H = 0$ and $\mathcal{L}_{X^3}i_{X^1}i_{X^2}H = \mathcal{L}_{\partial_3}(-x^2dx^3) = 0$. Then $eadx^2 = 0$. So, $a = 0$ or $e = 0$.

If $(b_1, b_2, c_1, c_2) = (-a, a, a, 0)$, the above equality is equivalent to

$$ea \sum \{i_{X^1} i_{[X^2, X^3]} H + \mathcal{L}_{X^1} i_{X^2} i_{X^3} H\} = ead i_{X^1} i_{X^2} i_{X^3} H,$$

where \sum is the cyclic sum $\sum_{cycl(X^1, X^2, X^3)}$. Then e is arbitrary real number because from $dH = 0$ it follows

$$\sum \{i_{X^1} i_{[X^2, X^3]} H + \mathcal{L}_{X^1} i_{X^2} i_{X^3} H\} = di_{X^1} i_{X^2} i_{X^3} H.$$

Indeed, using $dH = 0$ and $i_{[X^1, X^4]} = \mathcal{L}_{X^1} i_{X^4} - i_{X^4} \mathcal{L}_{X^1}$ and the well-known formula expressing $dH(X^1, X^2, X^3, X^4)$, we have

$$\begin{aligned} & \sum \{i_{X^4} i_{X^1} i_{[X^2, X^3]} H + i_{X^4} \mathcal{L}_{X^1} i_{X^2} i_{X^3} H\} \\ &= \sum \{i_{X^4} i_{X^1} i_{[X^2, X^3]} H + \mathcal{L}_{X^1} i_{X^4} i_{X^2} i_{X^3} H - i_{[X^1, X^4]} i_{X^2} i_{X^3} H\} \\ &= 6 \sum \{H([X^2, X^3], X^1, X^4) + X^1 H(X^3, X^2, X^4) \\ & \quad - H(X^3, X^2, [X^1, X^4])\} \\ &= -24dH(X^1, X^2, X^3, X^4) + 6X^4 H(X^3, X^2, X^1) = i_{X^4} di_{X^1} i_{X^2} i_{X^3} H. \end{aligned}$$

Summing up, given a real number $a \neq 0$ we have $(b_1, b_2, c_1, c_2, e) = (0, 0, 0, 0, 0)$ or $(b_1, b_2, c_1, c_2, e) = (0, a, 0, 0, 0)$ or $(b_1, b_2, c_1, c_2, e) = (-a, a, 0, 0, 0)$ or $(b_1, b_2, c_1, c_2, e) = (-a, a, a, 0, e)$, where e may be arbitrary real number. If $a = 0$ we have $(b_1, b_2, c_1, c_2, e) = (0, 0, 0, 0, e)$, where e may be arbitrary. Theorem 5.3 is complete. \square

Corollary 5.4. *If $m \geq 3$, then the twisted Courant bracket $\mathcal{M}f_m$ -natural operator from Example 3.2 is the unique $\mathcal{M}f_m$ -natural operator A in the sense of Definition 3.1 for $p = 3$ satisfying the following conditions:*

- (C1) $A_H(\rho_1, A_H(\rho_2, \rho_3)) = A_H(A_H(\rho_1, \rho_2), \rho_3) + A_H(\rho_2, A_H(\rho_1, \rho_3))$,
- (C2) $A_H(X \oplus 0, Y \oplus 0) = [X, Y] \oplus i_X i_Y H$

for all $\rho_1, \rho_2, \rho_3, X \oplus 0, Y \oplus 0 \in \mathcal{X}(M) \oplus \Omega^1(M)$, all closed $H \in \Omega_{cl}^3(M)$ and all m -manifolds M .

Proof. Indeed, the condition (C1) and Theorem 5.3 imply that $A = A^{(1,a)}$ or $A = A^{(2,a)}$ or $A = A^{(3,a)}$ or $A = A^{(4,a,e)}$ for some real numbers a and e . Then (C2) implies that $A = A^{(4,a,e)}$ and $a = 1$ and $e = 1$ because $A_H^{(1,a)}(X \oplus 0, Y \oplus 0) = a[X, Y] \oplus 0$ and $A_H^{(2,a)}(X \oplus 0, Y \oplus 0) = a[X, Y] \oplus 0$ and $A_H^{(3,a)}(X \oplus 0, Y \oplus 0) = a[X, Y] \oplus 0$ and $A_H^{(4,a,e)}(X \oplus 0, Y \oplus 0) = a[X, Y] \oplus ei_X i_Y H$. \square

Corollary 5.5. *If $m \geq 3$, any $\mathcal{M}f_m$ -natural operator A in the sense of Definition 3.1 for $p = 3$ such that A_H is a Lie algebra bracket (i.e., it is skew-symmetric, bilinear and satisfying the Leibniz rule) for all closed 3-forms $H \in \Omega_{cl}^3(M)$ and all m -manifolds M is one of the $\mathcal{M}f_m$ -natural operators:*

$$\begin{aligned} A_H^{(1,a)}(\rho_1, \rho_2) &= a[X^1, X^2] \oplus 0, \\ A_H^{(2,a)}(\rho^1, \rho^2) &= a[X^1, X^2] \oplus (a(\mathcal{L}_{X^1} \omega^2 - \mathcal{L}_{X^2} \omega^1)), \\ A_H^{(4,0,e)}(\rho^1, \rho^2) &= 0 \oplus ei_{X^1} i_{X^2} H, \end{aligned}$$

where $\rho^1 = X^1 \oplus \omega^1$ and $\rho^2 = X^2 \oplus \omega^2$, and a and e are arbitrary real numbers.

Proof. It follows from Theorem 5.3. □

Corollary 5.6. *If $m \geq 3$, any $\mathcal{M}f_m$ -natural operator A in the sense of Definition 3.1 for $p = 3$ satisfying the Leibniz rule for all 3-forms H (or for all closed 3-forms and at least one non-closed 3-form) is one of the $\mathcal{M}f_m$ -natural operators:*

$$\begin{aligned} A_H^{(1,a)}(\rho_1, \rho_2) &= a[X^1, X^2] \oplus 0, \\ A_H^{(2,a)}(\rho^1, \rho^2) &= a[X^1, X^2] \oplus (a(\mathcal{L}_{X^1}\omega^2 - \mathcal{L}_{X^2}\omega^1)), \\ A_H^{(3,a)}(\rho^1, \rho^2) &= a[X^1, X^2] \oplus (a\mathcal{L}_{X^1}\omega^2), \\ A_H^{(4,a,0)}(\rho^1, \rho^2) &= a[X^1, X^2] \oplus (a(\mathcal{L}_{X^1}\omega^2 - i_{X^2}d\omega^1)), \\ A_H^{(4,0,e)}(\rho^1, \rho^2) &= 0 \oplus ei_{X^1}i_{X^2}H, \end{aligned}$$

where $\rho^1 = X^1 \oplus \omega^1$ and $\rho^2 = X^2 \oplus \omega^2$, and a and e are arbitrary real numbers.

Proof. It follows from Theorem 5.3 and its proof. □

Remark 5.7. It is well-known that given closed 3-form $H \in \Omega_{cl}^3(M)$ on a m -manifold M , the twisted Courant bracket $[-, -]_H : (\mathcal{X}(M) \oplus \Omega^1(M)) \times (\mathcal{X}(M) \oplus \Omega^1(M)) \rightarrow \mathcal{X}(M) \oplus \Omega^1(M)$ is bilinear and satisfies the properties (A1)–(A5) from Corollary 2.8 for all $\rho_1, \rho_2, \rho_3 \in \mathcal{X}(M) \oplus \Omega^1(M)$ and all $f \in C^\infty(M)$, see [3, 8], but $[-, -]_H \neq [-, -]_0$ if $H \neq 0$. Is it a contradiction with the uniqueness from Corollary 2.8? No, it is not. Indeed, $[-, -]_H$ is not extendable to a $\mathcal{M}f_m$ -natural bilinear operator in the sense of Definition 2.1 because it is invariant only with respect to $\mathcal{M}f_m$ -maps $\varphi : M \rightarrow M$ preserving H , in fact.

Remark 5.8. By Corollary 5.5, given a closed 3-form H on M , the skew-symmetric bracket $[[X^1 \oplus \omega^1, X^2 \oplus \omega^2]]^{(H)} := 0 \oplus i_{X^1}i_{X^2}H$ satisfies the Leibniz rule. One can easily directly verify that $(TM \oplus T^*M, e[[-, -]]^{(H)}, 0\pi)$ for arbitrary fixed $e \in \mathbf{R}$ and closed 3-form H is a Lie algebroid canonically depending on H . So, if we have a closed 3-form H on a m -manifold M , we can construct canonical (in H) Lie algebroids $(EM, [[-, -]]^{[H]}, a^{[H]})$ with $EM = TM \oplus T^*M$ different than the one from Proposition 2.11.

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